

## **Haze Reduction from Remotely Sensed Data**

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### **Abstract**

Haze consists of atmospheric aerosols and molecules that scatter and absorb solar radiation, thus affecting the downward and upward solar radiance to be recorded by remote sensing sensors. Haze modifies the spectral signature of land classes and reduces classification accuracy, so causing problems to users of remote sensing data. Hence, there is a need to reduce the haze effects to improve the usefulness of the data. A way to do this is by integrating spectral and statistical approaches. The result shows that the haze reduction method is able to increase the accuracy of the data statistically and visually.

**Keywords:** Remote Sensing, Haze Reduction, Spectral

### **1 Introduction**

Haze is a common problem in Malaysian remote sensing data, particularly those acquired at the end of the year. Haze occurrences in Malaysia are associated with large-scale forest fire from neighbouring countries due to forest clearing activities

[1], [2]. Haze affects the properties of remote sensing data and can cause serious inaccuracy in further processing stages (e.g. classification) [3], [4], [5]. Haze is caused by atmospheric scattering and absorption due to haze constituents in which depend substantially on the wavelength of the solar radiation. Scattering is usually much stronger for short wavelengths than for long wavelengths and significantly affects the classification of surface features from remote sensing data. In order for the hazy data to be usable again, this study attempts to develop a practical haze reduction technique. Haze reduction, in practice, should be usable at any time and independent from auxiliary information, such as haze path radiance and meteorological information [6], which is unavailable in most cases due to a lack of ground stations. Initially, researchers in this area attempted to determine and remove uniform haze path radiance, but later spatially-varying haze was taken into account.

In the early years, the most popular procedure was dark-object subtraction (DOS), which considers uniform haze [7]. In order to determine the haze path radiance, it is assumed that there are some pixels within the image that are totally black (dark objects); this is usually caused by topography or cloud shadows. A dark object is assumed to be unable to reflect any solar energy and thus should possess zero DN (digital number) or zero reflectance. If haze exists, these pixels do not appear completely dark because solar energy is scattered into the satellite's field of view by the haze. From the histogram of a particular visible band, this effect can be seen as a sharp increase in occurrence frequency in the lower DN region. The DN value that corresponds to this increase is assumed to be the amount of haze in that particular band. This needs to be subtracted from the entire image for that band to correct for the haze, although smaller occurring DNs may also represent haze. Although this is easy and practical, it is quite ambiguous in most cases, since the shadow pixels caused by topography and clouds may not actually have zero DN due to secondary energy scattered from other objects into the shadowed area; thus the haze value selected from the histogram may not correspond to a real dark object. This can lead to over-reduction for haze and consequently cause truncation of the values for some surface pixels. Hence, this method is not considered further.

Scott et al. [8] developed a scene-to-scene radiometric normalisation technique for haze reduction that is based on the statistical invariance of the reflectance possessed by objects known as pseudoinvariant features (PIF). For a scene, Scott et al. [8] suggested that the PIF pixels could be chosen from man-made objects such as road surfaces, rooftops and parking lots. For a feature (e.g. road surfaces), one or more pixels can be chosen, depending on the size of the feature (more pixels can be chosen from a large PIF provided they have nearly constant reflectance); however, Scott et al. [8] did not discuss in detail the minimum size requirement for a single PIF. The relationship between PIF pixels from a hazy scene and from a clear reference scene is assumed to be represented by a linear

equation, which can be generated by regressing the DNs of PIF pixels from a hazy dataset against those of a reference dataset from the same band. The entire hazy dataset is then transformed using this linear equation. Unlike the DOS method that uses dark features that produce a weak radiance, the PIF method uses bright surfaces. Hence, the additive effects of secondary scattering on the PIFs can be neglected. However, the method is less effective when dealing with non-uniform haze.

Liang et al. [6] presented a haze reduction method that takes into account non-uniform haze within a Landsat dataset, by combining image-based and radiative transfer equation approaches. Initially, the near-infrared bands 4, 5 and 7, which are less affected by haze, are used to classify pixels into cover types. For this purpose, they used an unsupervised classification method, where 20 to 50 clusters are generated, depending on the complexity of the landscape. They then separated clear and the hazy regions by enhancing the boundaries between hazy and clear regions and then visually analysing and drawing the hazy regions using image processing software. Liang et al. [6] suggested that the boundaries can be enhanced using one of the following methods: (i) the fourth component of the Tasseled Cap transformation [9], (ii) the ratio of bands 1 and 4 or (iii) the visible bands 1, 2 and 3; the last one is often used because it is simple and effective. Next, they determined the mean reflectances of clear regions and matched with those of the hazy region from the same cluster. They then subtracted the mean reflectances of the cluster from the hazy reflectances in order to determine the haze reflectance. With the assumption that the distribution of haze reflectance is smoother than surface reflectance, Liang et al. [6] subsequently used a low-pass smoothing to determine the distribution of the haze reflectance in each band. Finally, they determined the corrected surface reflectance for each band by subtracting the corresponding haze reflectance from the hazy data. Liang et al. [6] claimed the method visually removed non-uniform haze from bands 1, 2 and 3.

## 2 Materials and Methods

The study area is Bukit Beruntung in Selangor, Malaysia from a 400 x 400 Landsat dataset dated 6 August 2005. The date is chosen because the area contains very less cloud and covered with non-uniform haze that is to be removed in this study. Initially cloud and cloud shadow are detected using threshold method and masked black [10]. Water body is then detected using the same method and masked white. The Bands 3, 2 and 1, which are significantly affected by haze, are first used to visually determine the hazy and clear regions (Figure 1(a)); this is done by enhancing the hazy-clear regions using contrast manipulation method (i.e. contrast stretching) and delineating a boundary between them using the built-in applications in the image processing software (Figure 1(b)). Next, Bands 4, 5 and 7 (Figure 1(c)), which are less affected by haze, are used as input for ISODATA clustering to produce 35 clusters for the entire area (Figure 1(d)) [5].

Subsequently, the hazy-clear regions developed are used as a template for the 35-clusters map. By doing so, each cluster is subdivided into two parts: the parts that fall within the hazy region and the clear region. For each cluster, pixel reflectances from the hazy region are replaced with the mean reflectance from the clear region; this process is carried out for all 35 clusters and for visible bands 1, 2 and 3. Infrared bands 4, 5 and 7 are assumed unaffected by the haze and therefore do not need any haze reduction. Bands 3, 2 and 1 assigned to red, green and blue channels after the mean reflectance replacement (Figure 1(e)). Next, the haze reflectance in each band is determined by subtracting the mean reflectances from the hazy data (Figure 1(f)) and then filtering it with a  $5 \times 5$  average filter (Figure 1(g)). Finally, the haze reflectance is subtracted from rest of the hazy data (i.e. bands 2 and 3) in order to determine the corrected surface reflectances for those bands (Figure 1(h)). The performance of the haze reduction is initially done through visual analysis. Next, Maximum Likelihood (ML) classification is carried out on the dataset before and after haze reduction and the performance is further verified based on their classification accuracy. This is done by using a confusion matrix, with respect to the clear image.

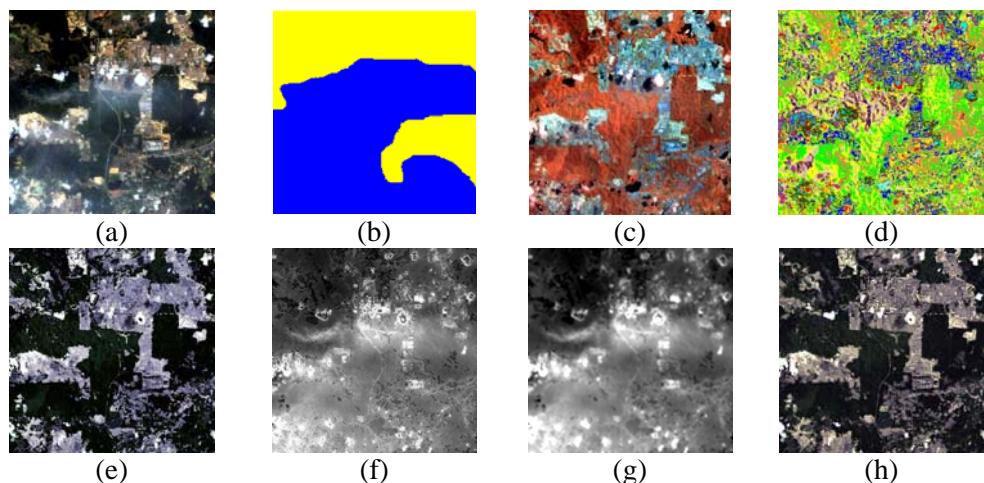


Fig. 1. The outcome of applying the haze reduction method: (a) bands 3, 2 and 1 assigned to red, green and blue channel, (b) the corresponding hazy (blue) and clear (yellow) regions, (c) bands 4, 5 and 7 assigned to red, green and blue channel, (d) the 35-clusters map generated using the ISODATA clustering, (e) same as (a) but after mean reflectances replacement, (f) the result after subtracting (e) from band 1 in (a), (g) same as (f) but after  $5 \times 5$  average filtering and (h) same as (a) but after subtracting the haze reflectance in each band.

### 3 Results and Discussion

Figure 2 shows the datasets (a) before, (b) after haze reduction and (c) a clear dataset dated 22 August 2005 as reference. The top rows are colour composite images of band 3, 2 and 1 assigned to red, green and blue (top row) respectively. The middle row shows the corresponding ML classification and the bottom row

are the enlarged version of the middle row. The enlarged version represents the area within the yellow box in the ML classification image. From the top row, it is clear that after undergoing the haze reduction, the haze has been removed from the dataset and the edges of certain features, e.g. roads and urban areas, have been restored. The dataset seems a little brighter compared to before reduction; this is probably due to the smaller dynamic range of pixel values when displayed under the same brightness range. However, some detailed structures within the urban areas are lost. This is mainly due to the effects of clustering and mean reflectances replacement, which heavily depends on the accuracy of the hazy-clear boundary. For the classification image, after haze reduction, most cleared land pixels (purple) that appeared within the urban (red) vanished; however this seems to be overdone when compared to the clear one. Unexpectedly, it is also noticed that after haze reduction, some land pixels are misclassified as water. This can be further explained by using a confusion matrix. Table 1 shows the confusion matrix of the classification images (a) before and (b) after haze reduction with respect to the clear dataset. The overall accuracy increases only 0.1% (i.e. 74.9%) compared to the hazy dataset (i.e. 75.0%), and no change for kappa coefficient (i.e. 0.616). This indicates that very small improvement in overall classification accuracy is obtained when using the haze reduction method. It is believed that this is mainly due to the highly non-uniform haze within the hazy dataset that hampered the performance of the haze reduction process. The diagonal elements in Table 1 represent the percentage of the correctly assigned pixels or also known as the accuracy of the individual classes. The accuracy of water, rubber, cleared land and urban before haze reduction are 72.51%, 89.58%, 59.05% and 66.59% respectively while those of after reduction are 75.45%, 89.14%, 50.04 and 74.91% respectively. This indicates that an improvement in accuracy of 2.94% and 8.32% occurs in water and urban respectively. However, rubber and cleared land experience a decrease of 0.44% and 9.01% respectively. In terms of the statistical properties of the classes, after the haze reduction, the mean radiances for urban and rubber are slightly lower compared to those of before haze reduction (Table 2). This is again may be due to the nature of the reduction procedures that replaces the pixels within hazy regions with the mean values of the same cluster but from clear regions. After haze reduction, all classes mostly have smaller standard deviations in all bands compared to those of before reduction (Table 2). This indicates after the reduction, the training pixels collected, have purer spectral signatures and thus producing better classification compared to before reduction. The mean separation after reduction is smaller compared to before, while the clear image, as expected, possesses the largest separation.

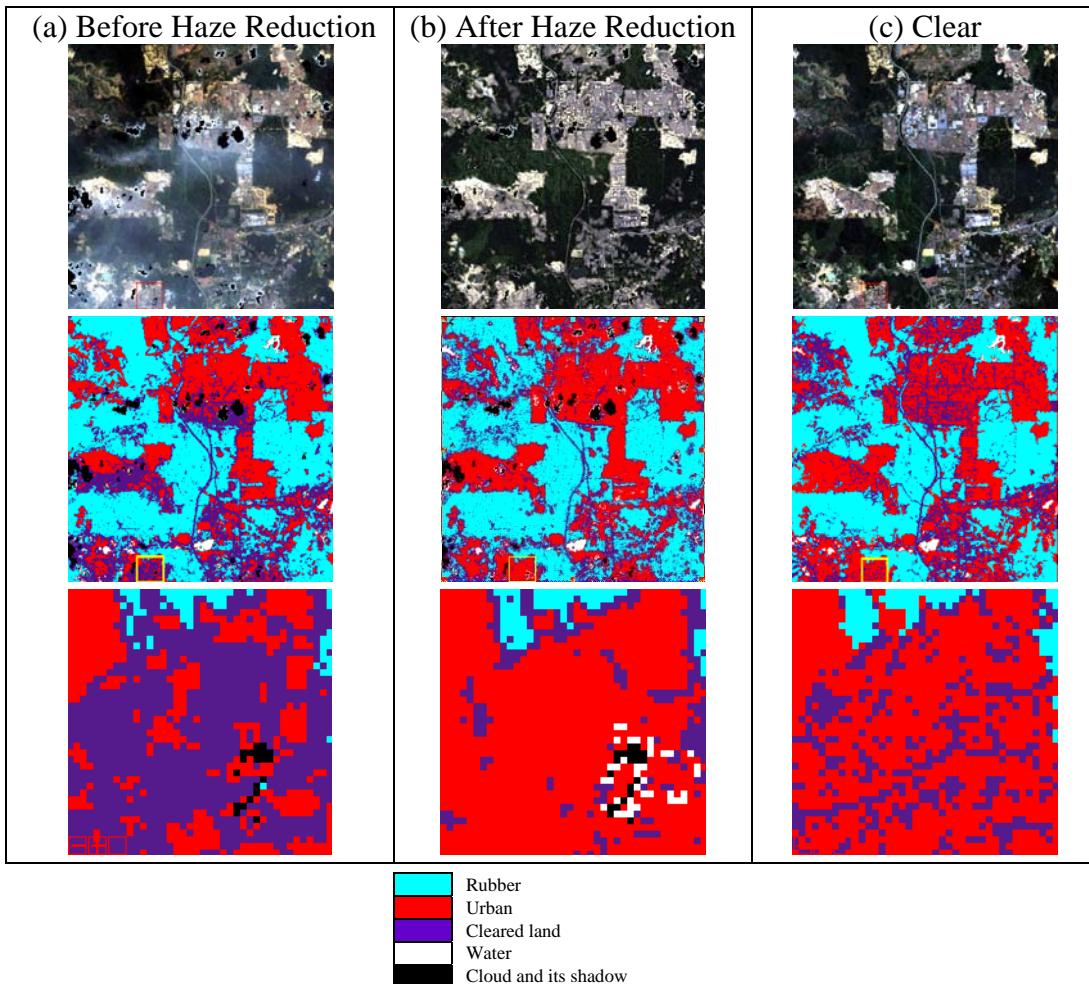


Fig. 2. Colour composite image of band 3, 2 and 1 assigned to red, green and blue (top row) respectively, ML classification (middle row) and the corresponding enlarged version (bottom row) before and after haze reduction (left and middle column) and the clear image (right column). The enlarged version represents the area within the yellow box in the ML classification image.

Table 1: Confusion matrix (a) before and (b) after haze reduction with respect to the clear image.

Class	Clear Image (Percent)				Total
	Water	Rubber	Cleared Land	Urban	
Water	72.51	0.04	0.42	1.38	1.19
Rubber	7.44	89.58	18.61	3.12	44.99
Cleared Land	8.02	9.8	59.05	28.92	27.78
Urban	12.03	0.57	21.92	66.59	26.04
Total	100	100	100	100	100

Overall Accuracy = 74.9%

Kappa Coefficient = 0.616

(a)

Class	Clear Image (Percent)				Total
	Water	Rubber	Cleared Land	Urban	
Water	75.45	0.22	0.68	1.46	1.39
Rubber	5.73	89.14	24.06	3.71	46.31
Cleared Land	8.02	8.69	50.04	19.92	22.33
Urban	10.81	1.94	25.21	74.91	29.97
Total	100	100	100	100	100

Overall Accuracy = 75.0%

Kappa Coefficient = 0.616

(b)

Table 2: Mean and standard deviation for cleared land, rubber and urban: (a) before removal, (b) after removal and (c) reference dataset.

Rubber			Cleared Land		Urban		Rubber			Cleared Land		Urban	
Band	Mean	Stdev	Mean	Stdev	Mean	Stdev	Band	Mean	Stdev	Mean	Stdev	Mean	Stdev
1	69.03	8.12	75.58	10.27	83.16	11.55	1	64.17	2.46	68.68	5.03	74.24	6.09
2	53.73	7.86	63.02	10.16	73.36	13.25	2	50.51	3.01	56.96	6.68	64.99	9.16
3	36.34	7.07	47.42	10.57	61.52	14.88	3	34.30	3.13	42.66	8.44	53.66	11.28
4	70.90	8.35	68.97	9.02	65.22	9.92	4	70.73	8.16	68.81	8.88	65.20	9.71
5	7.92	1.29	10.00	1.83	12.18	3.14	5	8.19	1.02	9.90	1.87	11.88	2.87
7	1.47	0.33	2.28	0.65	3.25	1.06	7	1.53	0.24	2.19	0.64	3.00	0.86

(a)			(b)		
Band	Mean	Stdev	Mean	Stdev	Mean
1	49.88	1.84	59.64	7.50	70.13
2	37.07	2.76	50.99	8.25	66.09
3	21.99	2.21	38.24	9.55	60.24
4	71.84	11.02	69.04	10.31	61.55
5	7.39	1.24	9.94	1.65	12.75
7	1.13	0.23	2.13	0.62	3.36

(c)

## 4 Conclusions

In overall, the haze reduction method is able to remove haze and produce classification with slightly higher accuracy compared to that of before haze reduction. The performance is hampered by the need to use visual analysis in determining the hazy-clear boundary. An objective method to do so is needed in order to improve the results.

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